Course Learning Objectives is to

- Understand energy scenario, energy sources and their utilization
- Learn about energy conversion methods and their analysis
- Study the principles of renewable energy conversion systems
- Understand the concept of green energy and zero energy.

Module – I

**Thermal Energy Conversion System:** Review of energy scenario in India, General Philosophy and need of Energy, Different Types of Fuels used for steam generation, Equipment for burning coal in lump form, strokers, different types, Oilburners, Advantages and Disadvantages of using pulverized fuel, Equipment for preparation and burning of pulverized coal, unit system and bin system, Pulverized fuel furnaces, cyclone furnace, Coal and ash handling, Generation of steam using forced circulation, high and supercritical pressures. Chimneys: Natural, forced, induced and balanced draft, Calculations and numerical involving height of chimney to produce a given draft. Cooling towers and Ponds. Accessories for the Steam generators such as Superheaters, De-superheater, control of superheaters, Economizers, Air preheaters, and re-heaters.

**9 Hours**

Module – II

**Diesel Engine Power System:** Applications of Diesel Engines in Power field. Method of starting Diesel engines. Auxiliaries like cooling and lubrication system, filters, centrifuges, Oil heaters, intake and exhaust system, Layout of diesel power plant.

**Hydro-Electric Energy:** Hydrographs, flow duration and mass curves, unit hydrograph and numerical. Storage and pondage, pumped storage plants, low, medium and high head plants, Penstock, water hammer, surge tanks, gates, and valves. General layout of hydel power plants.

**7 Hours**

Module – III

**Solar Energy:** Fundamentals; Solar Radiation; Estimation of solar radiation on horizontal and inclined surfaces; Measurement of solar radiation data. Solar Thermal systems: Introduction; Basics of thermodynamics and heat transfer; Flat plate collector; Evacuated Tubular Collector; Solar air collector; Solar concentrator; Solar distillation; Solar cooker; Solar refrigeration and air conditioning; Thermal energy storage systems, Solar Photovoltaic systems: Introduction; Solar cell Fundamentals; Characteristics and classification; Solar cell: Module, panel and Array construction; Photovoltaic thermal systems

**8 Hours**

Module – IV
**Wind Energy**: Properties of wind, availability of wind energy in India, wind velocity and power from wind; major problems associated with wind power, wind machines; Types of wind machines and their characteristics, horizontal and vertical axis wind mills, coefficient of performance of a wind mill rotor (Numerical Examples).

**Tidal Power**: Tides and waves as energy suppliers and their mechanics; fundamental characteristics of tidal power, harnessing tidal energy, limitations.

**Module – V**

**Biomass Energy**: Introduction; Photosynthesis Process; Biofuels; Biomass Resources; Biomass conversion technologies; Urban waste to energy conversion; Biomass gasification.

**Green Energy**: Introduction: Fuel cells: Overview; Classification of fuel cells; Operating principles; Fuel cell thermodynamics; Nuclear, ocean, MHD, thermoelectric and geothermal energy applications; Origin and their types; Working principles, Zero energy Concepts

**Course Outcomes**
At the end of the course, the student will be able to:
- Summarize the basic concepts of thermal energy systems,
- Identify renewable energy sources and their utilization.
- Understand the basic concepts of solar radiation and analyze the working of solar PV and thermal systems.
- Understand principles of energy conversion from alternate sources including wind, geothermal, ocean, biomass, biogas.
- Understand the concepts and applications of fuel cells, thermoelectric convertor and MHD generator.
- Identify methods of energy storage for specific applications

**TEXT BOOKS:**

**REFERENCE BOOKS:**

**Scheme of Examination**: Two question to be set from each module. Students have to answer five full questions, choosing at least one full question from each module.
FLUID POWER SYSTEMS

<table>
<thead>
<tr>
<th>Course</th>
<th>Code</th>
<th>Credits</th>
<th>L-T-P</th>
<th>Assessment</th>
<th>Exam Duration</th>
</tr>
</thead>
<tbody>
<tr>
<td>Fluid Power Systems</td>
<td>15ME72</td>
<td>04</td>
<td>3-2-0</td>
<td>80</td>
<td>20</td>
</tr>
</tbody>
</table>

Course objectives:

<table>
<thead>
<tr>
<th>CLO1</th>
<th>To provide an insight into the capabilities of hydraulic and pneumatic fluid power.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CLO2</td>
<td>To understand concepts and relationships surrounding force, pressure, energy and power in fluid power systems.</td>
</tr>
<tr>
<td>CLO3</td>
<td>To examine concepts centering on sources of hydraulic power, rotary and linear actuators, distribution systems, hydraulic flow in pipes, and control components in fluid power systems.</td>
</tr>
<tr>
<td>CLO4</td>
<td>Exposure to build and interpret hydraulic and pneumatic circuits related to industrial applications.</td>
</tr>
<tr>
<td>CLO5</td>
<td>To familiarize with logic controls and trouble shooting.</td>
</tr>
</tbody>
</table>

Module 1: Introduction to fluid power systems


10 hours

Module 2: Pumps and actuators

Pumps: Classification of pumps, Pumping theory of positive displacement pumps, construction and working of Gear pumps, Vane pumps, Piston pumps, fixed and variable displacement pumps, Pump performance characteristics, pump selection factors, problems on pumps.

Accumulators: Types, selection/design procedure, applications of accumulators. Types of Intensifiers, Pressure switches/sensor, Temperature switches/sensor, Level sensor.

Actuators: Classification cylinder and hydraulic motors, Hydraulic cylinders, single and double acting cylinder, mounting arrangements, cushioning, special types of cylinders, problems on cylinders.

Construction and working of rotary actuators such as gear, vane, piston motors, and Hydraulic Motor. Theoretical torque, power, flow rate, and hydraulic motor performance; numerical problems. Symbolic representation of hydraulic actuators (cylinders and motors).

10 hours

Module 3: Components and hydraulic circuit design
**Components:** Classification of control valves, Directional Control Valves - symbolic representation, constructional features of poppet, sliding spool, rotary type valves solenoid and pilot operated DCV, shuttle valve, and check valves.

Pressure control valves - types, direct operated types and pilot operated types.

Flow Control Valves - compensated and non-compensated FCV, needle valve, temperature compensated, pressure compensated, pressure and temperature compensated FCV, symbolic representation.

**Hydraulic Circuit Design:** Control of single and Double -acting hydraulic cylinder, regenerative circuit, pump unloading circuit, double pump hydraulic system, counter balance valve application, hydraulic cylinder sequencing circuits, cylinder synchronizing circuit using different methods, hydraulic circuit for force multiplication; speed control of hydraulic cylinder - metering in, metering out and bleed off circuits. Pilot pressure operated circuits. Hydraulic circuit examples with accumulator.

10 hours

**Module 4: Pneumatic power systems**

*Introduction to Pneumatic systems:* Pneumatic power system, advantages, limitations, applications, Choice of working medium. Characteristics of compressed air and air compressors. Structure of pneumatic control system, fluid conditioners - dryers and FRL unit.

Pneumatic Actuators: Linear cylinder - types of cylinders, working, end position cushioning, seals, mounting arrangements, and applications. Rotary cylinders - types, construction and application, symbols.

Pneumatic Control Valves: DCV such as poppet, spool, suspended seat type slide valve, pressure control valves, flow control valves, types and construction, use of memory valve, Quick exhaust valve, time delay valve, shuttle valve, twin pressure valve, symbols.

10 hours

**Module 5: Pneumatic control circuits**

Simple Pneumatic Control: Direct and indirect actuation pneumatic cylinders, speed control of cylinders - supply air throttling and exhaust air throttling.

Signal Processing Elements: Use of Logic gates - OR and AND gates in pneumatic applications. Practical examples involving the use of logic gates.

Multi-Cylinder Application: Coordinated and sequential motion control, motion and control diagrams. Signal elimination methods, Cascading method-principle, Practical application examples (up to two cylinders) using cascading method (using reversing valves).

Electro-Pneumatic Control: Principles - signal input and output, pilot assisted solenoid control of directional control valves, use of relay and contactors. Control circuitry for simple signal cylinder application.

10 hours

**COURSE OUTCOMES:**

After studying this course, students will be able to:

<p>| CO1 | Identify and analyse the functional requirements of a fluid power transmission system for a |</p>
<table>
<thead>
<tr>
<th>CO2</th>
<th>Visualize how a hydraulic/pneumatic circuit will work to accomplish the function.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CO3</td>
<td>Design an appropriate hydraulic or pneumatic circuit or combination circuit like electro-hydraulics, electro-pneumatics for a given application.</td>
</tr>
<tr>
<td>CO4</td>
<td>Select and size the different components of the circuit.</td>
</tr>
<tr>
<td>CO5</td>
<td>Develop a comprehensive circuit diagram by integrating the components selected for the given application.</td>
</tr>
</tbody>
</table>

**TEXT BOOKS:**

**REFERENCE BOOKS:**

**Scheme of Examination:**
Two questions to be set from each module. Students have to answer five full questions, choosing one full question from each module.

**Learning Assignment:**
The faculty will allocate one or more of the following experiments from group A and B to group of students (containing not more than four students in a group):

**Group A: Experiments on hydraulic trainer:**
- a. Speed control circuit using metering in and metering out technique
- b. Regenerative and sequencing circuits.
- c. Extend-Retract and Stop system of a linear actuator
- d. Rapid Traverse and Feed circuit.

**Group B: Experiments on pneumatic trainer:**
- a. Automatic reciprocating circuit
- b. Speed control circuit
- c. Pneumatic circuit involving shuttle valve/quick exhaust valve
- d. Electro pneumatic valves and circuit

Students should build up the above circuits on computer using software and simulate the flow of fluid during the operation. Afterwards, they themselves can physically connect the circuit on the hydraulic/pneumatic trainer and run the circuit. Record of experiments shall be submitted in the form of journal. Due credit must be given for this assignment (5 Marks).

**List of Open Source Software/learning website:**
1. Simulink
2. SimHydraulics
CONTROL ENGINEERING

<table>
<thead>
<tr>
<th>Course</th>
<th>Code</th>
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<th>L-T-P</th>
<th>Assessment</th>
<th>Exam Duration</th>
</tr>
</thead>
<tbody>
<tr>
<td>Control Engineering</td>
<td>15ME73</td>
<td>04</td>
<td>3-2-0</td>
<td>80 20</td>
<td>3Hrs</td>
</tr>
</tbody>
</table>

Course Objectives

1. Modeling of mechanical, hydraulic, pneumatic and electrical systems.
2. Representation of system elements by blocks and its reduction.
3. Transient and steady state response analysis of a system.
4. Frequency response analysis using polar plot.
5. Frequency response analysis using bode plot.
6. Analysis of system using root locus plots.
7. Different system compensators and variable characteristics of linear systems.

MODULE 1

Introduction: Concept of automatic controls, Open loop and closed loop systems, Concepts of feedback, requirements of an ideal control system, Types of controllers-Proportional, Integral, Differential, Proportional & Integral, Proportional Differential and Proportional Integral Differential controllers.  

(7 Hours)

MODULE 2

(3 hours)

Analogous Systems: Direct and inverse analogs for mechanical, thermal and fluid systems.  
(4 hours)

Block diagram Algebra: General representation of a feedback control system, transfer functions, rules of block diagram algebra, reduction of block dia. to obtain closed loop transfer function.  

Signal flow graphs: Mason’s gain formula  
(6 Hours)
MODULE 3

**Steady state operation:** Steady state analysis for general block dia. for a control system, steady state characteristics, equilibrium in a system. (3 hours)

**Transient Response:** Transient response and steady state analysis of unit, step input, general operational representation for a differential equation of control system, distinct, repeated and complex conjugate zeros, general form of transient response, Routh’s stability criterion for a control system. (4 hours)

**Root Locus Plots:** Root locus method: Significance of Root locus, angle and magnitude conditions, breakaway points, angles of departure and arrival, construction of Root locus using general rules and steps, Lead and Lag compensation. (6 Hours)

MODULE 4

**Frequency Domain Analysis:** Relationship between time and frequency response, Polar plot, Bode’s Plot, Nyquist plot and Nyquist stability criterion, Relative Stability, Phase and Gain Margins (14 Hours)

MODULE 5

**System Compensation and State Variable Characteristics of Linear Systems:** Series and feedback compensation, Introduction to state concepts, state equation of linear continuous data system. Matrix representation of state equations, controllability and observability, Kalman and Gilberts test. (7 Hours)

**Course Outcomes**

<table>
<thead>
<tr>
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</thead>
<tbody>
<tr>
<td>CO1: Recognize control system and its types, control actions</td>
</tr>
<tr>
<td>CO2: Determine the system governing equations for physical models (Electrical, Thermal, Mechanical, Electro Mechanical)</td>
</tr>
<tr>
<td>CO3: Calculate the gain of the system using block diagram and signal flow graph</td>
</tr>
<tr>
<td>CO4: Illustrate the response of 1st and 2nd order systems</td>
</tr>
<tr>
<td>CO5: Determine the stability of transfer functions in complex domain and frequency domain</td>
</tr>
<tr>
<td>CO6: Employ state equations to study the controllability and observability</td>
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</table>
DESIGN OF THERMAL EQUIPMENTS

<table>
<thead>
<tr>
<th>Course</th>
<th>Code</th>
<th>Credits</th>
<th>L-T-P</th>
<th>Assessment</th>
<th>Exam Duration</th>
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<tr>
<td>Design of thermal Equipments</td>
<td>15ME741</td>
<td>03</td>
<td>3-0-0</td>
<td>SEE 80 CIA 20</td>
<td>3Hrs</td>
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Course objectives:
1. To understand types of heat exchanger
2. To study the design shell and tube heat exchanger
3. To study types and design of steam heat condenser and compact heat exchanger
4. To comprehend and design air cooled heat exchanger
5. To understand and to design air cooled heat exchanger, furnaces

Module I

Introduction To Heat Exchanger Design: Types of heat exchangers and their applications. Flow arrangements and temperature distributions in transfer type of heat exchangers. Overall heat transfer coefficient;- Clean overall heat transfer coefficient, dirt factor dirt overall heat transfer coefficient, dirt factors for various process services.

Double Pipe Heat Exchangers: Film coefficients for tubes and annuli, equivalent diameter of annuli, fouling factors, caloric or average fluid temperature, true temperature difference; Design calculation of double pipe heat exchanger, double pipe exchangers in series-parallel arrangements. 08 Hrs

Module II

Shell and tube heat exchangers - tube layouts, baffle spacing, classification of shell and tube exchangers, Design calculation of shell and tube heat exchangers, flow assignments: tube side flow area calculations; viscosity correction factor, shell side equivalent diameter, calculation of shell side heat transfer coefficient, evaluation for wall temperature, evaluation of overall heat transfer coefficient, Calculation of surface area. Calculations of tube side and shell side pressure drops. 08 Hrs

Module III

Steam Condensers: Specifications of other details as per TEMA standards. Flow arrangement for increased heat recovery: - lack of heat recovery in 1-2 exchangers true temperature difference in a 2-4-exchanger. Calculation procedure for steam condensers.

Compact Heat Exchangers: Introduction; definition of Geometric Terms: plate fin surface geometries and surface performance data; correlation of heat transfer and friction data; Goodness factor comparisons; specification of rating and sizing problems; calculation procedure for a rating problem. 08 Hrs
Module IV

**Air-Cooled Heat Exchangers:** Air as coolant for industrial processes; custom-built units; fin-tube systems for air coolers; fin-tube bundles; thermal rating; tube side flow arrangements; cooling air supply by fans; cooling air supply in natural draft towers.

**Furnaces And Combustion Chambers:** Introduction; process heaters and boiler; heat transfer in furnaces: - Heat source; Heat sink; refractory surfaces; heat transfer to the sink; Design methods: - Method of Lobo and Evans: Method of Wilson, Lobo and Hottel; The Orrok-Hudson equation; Wallenberg simplified method.

Module V

**Heat Pipes** - types and applications, operating principles, working fluids, wick structures, control techniques, pressure balance, maximum capillary pressure, liquid and vapor pressure drops, effective thermal conductivity of wick structures, capillary limitation on heat transport capability, sonic, entrainment, and boiling limitations, determination of operating conditions; Heat pipe design – fluid selection, wick selection, material selection, preliminary design considerations, heat pipe design procedure, determination of heat pipe diameter, design of heat pipe containers, wick design, entertainment and boiling limitations, design problems

**Course outcomes:**

1. To have complete knowledge of heat exchanger and its applications
2. To be able to design shell and tube heat exchanger
3. To be able to select and design of steam heat condenser and compact heat exchanger condenser and heat pipes for various applications

**TEXT BOOKS:**

**REFERENCE BOOKS:**
3. **Heat exchanger**- Kokac Thermal- hydraulic and design analysis.
Course objectives:

<table>
<thead>
<tr>
<th>CLO</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CLO1</td>
<td>To educate the students on the importance of friction, the related theories/laws of sliding and rolling friction and the effect of viscosity of lubricants.</td>
</tr>
<tr>
<td>CLO2</td>
<td>To expose the students to the consequences of wear, wear mechanisms, wear theories and analysis of wear problems.</td>
</tr>
<tr>
<td>CLO3</td>
<td>To make the students understand the principles of lubrication, lubrication regimes, theories of hydrodynamic and the advanced lubrication techniques.</td>
</tr>
<tr>
<td>CLO4</td>
<td>To expose the students to the factors influencing the selection of bearing materials for different sliding applications.</td>
</tr>
<tr>
<td>CLO5</td>
<td>To introduce the concepts of surface engineering and its importance in tribology.</td>
</tr>
</tbody>
</table>

Module 1

**Introduction to tribology**: Historical background, practical importance, and subsequent use in the field.

Lubricants: Types and specific field of applications. Properties of lubricants, viscosity, its measurement, effect of temperature and pressure on viscosity, lubrication types, standard grades of lubricants, and selection of lubricants.

8 hours

Module 2

**Friction**: Origin, friction theories, measurement methods, friction of metals and non-metals.

**Wear**: Classification and mechanisms of wear, delamination theory, debris analysis, testing methods and standards. Related case studies.

8 hours

Module 3

**Hydrodynamic journal bearings**: Friction forces and power loss in a lightly loaded journal bearing, Petroff’s equation, mechanism of pressure development in an oil film, and Reynolds’ equation in 2D.

Introduction to idealized journal bearing, load carrying capacity, condition for equilibrium, Sommerfeld’s number and its significance; partial bearings, end leakages in journal bearing, numerical examples on full journal bearings only.

10 hours

Module 4

**Plane slider bearings with fixed/pivoted shoe**: Pressure distribution, Load carrying capacity, coefficient of friction, frictional resistance in a fixed/pivoted shoe bearing, center of pressure, numerical examples.
Hydrostatic Lubrication: Introduction to hydrostatic lubrication, hydrostatic step bearings, load carrying capacity and oil flow through the hydrostatic step bearing, numerical examples.

Module 5
Introduction to Surface engineering: Concept and scope of surface engineering.
Surface modification – transformation hardening, surface melting, thermo chemical processes.
Surface Coating – plating, fusion processes, vapor phase processes.
Selection of coating for wear and corrosion resistance.

8 hours

COURSE OUTCOMES:
After studying this course, students will be able to:

| CO1 | Understand the fundamentals of tribology and associated parameters. |
| CO2 | Apply concepts of tribology for the performance analysis and design of components experiencing relative motion. |
| CO3 | Analyse the requirements and design hydrodynamic journal and plane slider bearings for a given application. |
| CO4 | Select proper bearing materials and lubricants for a given tribological application. |
| CO5 | Apply the principles of surface engineering for different applications of tribology. |

Scheme of Examination:
Two questions to be set from each module. Students have to answer five full questions, choosing one full question from each module.
Use of approved Design Data Handbook/charts can be permitted during the examination.

TEXTBOOKS:

REFERENCES:
5. “Basic Lubrication Theory”, A. Cameron, Ellis Hardwoods Ltd., UK.
**FINANCIAL MANAGEMENT**

<table>
<thead>
<tr>
<th>Course</th>
<th>Code</th>
<th>Credits</th>
<th>L-T-P</th>
<th>Assessment</th>
<th>Exam Duration</th>
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<tr>
<td>Financial Management</td>
<td>15ME743</td>
<td>03</td>
<td>3-0-0</td>
<td>80</td>
<td>3Hrs</td>
</tr>
</tbody>
</table>

**Subject Overview:** Finance is the lifeblood of any enterprise. Financial Management is imperative for efficient utilization and generation of monetary resources and funds. The subject deals with fundamental books and records of accounts with financial analysis. The subject imparts exposure to statutory levies to strengthen the understanding of government taxed and duties including the general sales tax structure. The subject includes concepts of market risks and returns to efficiently manage the cash and circumvent liquidity problems both at the individual and organizational levels. In the new CBCS scheme, topics on investment decisions and asset management decisions besides the financing decisions. The curriculum also includes costing and budgeting to enable budding engineers to make a comparative study of finance and economics and evaluate costs and revenues of engineering operations.

**MODULE - 1**


**STATUTORY LEVIES:** Forms of organization, direct and indirect taxes. Statutory Registration - excise Duty, central sales tax, VAT, service tax, central and state general Sales tax, international fund availability.

**MODULE - 2**

**WORKING CAPITAL MANAGEMENT:** Definition, need and factors influencing the working capital requirement. Determination of operating cycle, cash cycle and operating cycle analysis. Calculation of gross working capital and net working capital requirement.

**LONG TERM FINANCING:** Raising of finance from primary and secondary markets. Valuation of securities, features of convertible securities and warrants. Features of debt, types of debt instruments, return on investment (ROI) and credit rating of units. Shares, debentures.

**MODULE-3**

**INVESTMENT DECISIONS:** Inventory investment, Strategic investment, Ownership investments, lending investment, cash equivalent investment, factors affecting investment decisions, Capital Budgeting, disinvestment methods - public offer, sale of equity, cross holding
ASSET MANAGEMENT DECISIONS: Current Asset Management, Fixed Asset Management, Wealth management, engineering asset management (EAM) - asset maintenance technologies, asset reliability management, project management

06 Hours

MODULE - 4

RISK AND REQUIRED RETURN: Risk and return relationship, methods of measuring the risk, Business risk, financial risk, calculation of expected rate of return to the portfolio, financial theories - portfolio theory, capital asset pricing model, arbitrage pricing theory

06 Hours

RATIO ANALYSIS / ACCOUNTING RATIO: Liquidity ratio – Current ratio, quick ratio, turn over ratio, capital structure ratio- Debt – equity ratio, Coverage ratio, Profitability ratio, Profit margin, Return on assets, Activity ratios – Inventory turnover ratio, Debtors Turnover ratio. Preparation of the balance sheet from various ratios. Analysis of any one published balanced sheet.

07 Hours

MODULE - 5

COSTING: Classification of costs, preparation of cost sheet, absorption and variable costing, standard costing, job costing, process costing.

Classification of the variances analysis – material, labor and overhead variances.

06 Hours

BUDGETING: Types of budgets – Flexible budgets, preparation of cash budgets, purchase and production budgets and master budget, Budgetary control, advantages & limitations of budgeting.

06 Hours

Course Outcomes: Upon successful completion of the course, students will be able to:

1. Measure the returns from engineering projects of differing risks and present a risk-return tradeoff relationship (PO 4, 12)
2. Determine the financial ratios and profitability margins of projects to evaluate economic viability to accept or reject the project. (PO 11)
3. Evaluate cost break ups of engineering projects and processes to determine and control the prohibitive cost components (PO 11)
4. Apply a Engineering Asset Management techniques to evaluate the economic value of physical assets. (PO 1, 11, 12)

TEXTBOOKS:

2. Financial Accounting, Costing and Management Accounting, S. M. Maheshwari, 2000
REFERENCE BOOKS:


**Course Outcomes:** Upon successful completion of the course, students will be able to:

1. Measure the returns from engineering projects of differing risks and present a risk-return tradeoff relationship (PO 4, 12)
2. Determine the financial ratios and profitability margins of projects to evaluate economic viability to accept or reject the project. (PO 11)
3. Evaluate cost break ups of engineering projects and processes to determine and control the prohibitive cost components (PO 11)
4. Apply a Engineering Asset Management techniques to evaluate the economic value of physical assets. (PO 1, 11, 12)
Course objectives:

| CLO1 | To educate students on factors to be considered in designing parts and components with focus on manufacturability. |
| CLO2 | To expose the students to dimensional tolerances, geometric tolerances and true position tolerance techniques in manufacture. |
| CLO3 | To impart the knowledge on design considerations for designing components produced using various machining operations like turning, drilling, milling, grinding etc. |
| CLO4 | To educate the students on design rules and recommendations for processes like casting, welding, forgings powder metallurgy and injection moulding. |

Module 1:
Major phases of design, effect of material properties on design, effect of manufacturing processes on design. Material selection process- cost per unit property, weighted properties and limits on properties methods. Guidelines for design for manufacturability.
Cumulative effect of tolerance- Sure fit law and truncated normal law, problems.

Module 2:
Selective Assembly: Interchangeable part manufacture and selective assembly. Deciding the number of groups -model-1: group tolerance of mating parts equal, model- 2: total and group tolerances of shaft equal. Control of axial play- introducing secondary machining operations, and laminated shims; examples.
True positional theory: Comparison between coordinate and true position method offeature location. True position tolerance- virtual size concept, floating and fixed fasteners, projected tolerance zone and functional gages. Concept of Zero true position tolerance. Simple problems on true position tolerancing.

Module3:
Datum Features: Functional datum, datum for manufacturing, changing the datum;examples.
Component Design: Design features to facilitate machining: drills, milling cutters, keyways, Doweling procedures, counter sunk screws, Reduction of machined area, simplification by separation, simplification by amalgamation, Design for machinability, Design for economy, Design for clampability, Design for accessibility. Design for assembly
Module 4:
Design of components with casting considerations: Pattern, mould, and parting line. Cored holes and machined holes. Identifying the possible and probable parting lines. Castings requiring special sand cores. Designing to obviate sand cores.
Welding considerations: requirements and rules, redesign of components for welding; case studies.  

Module 5:
Forging considerations - requirements and rules-redesign of components for forging and case studies.
Design of components for powder metallurgy - requirements and rules-case studies.
Design of components for injection moulding- requirements and rules-case studies.  

8 hours

COURSE OUTCOMES:
After studying this course, students will be able to:

| CO1 | Describe the different types of manufacturing systems and compare their suitability for economic production of various components and products. |
| CO2 | Identify factors and causing mechanisms of the defects likely to occur with different manufacturing processes in producing mechanical products and the relevant design approaches to rectify them. |
| CO3 | Select proper materials and manufacturing processes for designing products/components by applying the relevant principles for ease and economic production. |
| CO4 | |

Scheme of Examination:
Two questions to be set from each module. Students have to answer five full questions, choosing one full question from each module.

TEXTBOOKS:

REFERENCES:
**SMART MATERIALS and MEMS**

<table>
<thead>
<tr>
<th>Course</th>
<th>Code</th>
<th>Credits</th>
<th>L-T-P</th>
<th>Assessment</th>
<th>Exam Duration</th>
</tr>
</thead>
<tbody>
<tr>
<td>Smart Materials and MEMS</td>
<td>15ME745</td>
<td>03</td>
<td>3-0-0</td>
<td>80</td>
<td>20</td>
</tr>
</tbody>
</table>

**Course Objective:**
This course provides a detailed overview to smart materials, piezoelectric materials structures and its characteristics. The study of Smart structures and modelling helps in Vibration control using smart materials in various applications. Helps to understand the principles and concepts of using MEMS, ER & MR Fluids for various applications.

**MODULE 1**

Unit 1: Introduction: Closed loop and Open loop Smart Structures. Applications of Smart structures, Piezoelectric properties. Inchworm Linear motor, Shape memory alloys, Shape memory effect-Application, Processing and characteristics.


**MODULE -2**

Unit-3 Electro rheological and Magneto rheological Fluids: Mechanisms and Properties, Characteristics, Fluid composition and behaviour, Discovery and Early developments, Summary of material properties. Applications of ER and MR fluids (Clutches, Dampers, others).

Unit-4FibreOptics: Introduction, Physical Phenomenon, Characteristics, Fibre optic strain sensors, Twisted and Braided Fibre Optic sensors, Optical fibres as load bearing elements, Crack detection applications, Integration of Fibre optic sensors and shape memory elements.

**MODULE-3**


MODULE -4


MODULE -5


Unit 10: Case Studies: MEMS Magnetic actuators, BP sensors, Microphone, Acceleration sensors, Gyro, MEMS Product development: Performance, Accuracy, Repeatability, Reliability, Managing cost, Market uncertainties, Investment and competition – 5hrs

TEXT BOOKS:


COURSE OUTCOMES:

1. Describe the methods of controlling vibration using smart systems and fabrication methods of MEMS.
2. Explain the principle concepts of Smart materials, structures, Fibre optics, ER & MR Fluids, Biomimetics and MEMS with principles of working.
3. Analyze the properties of smart structures, MEMS, with the applications and select suitable procedure for fabrication.
4. Summarize the methods and uses of Micro fabrications, Biomimetics, types of polymers used in MEMS, Fibre optics, piezoelectric sensing and actuation.
Automotive Electronics

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<thead>
<tr>
<th>Course</th>
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<tbody>
<tr>
<td>Automotive Electronics</td>
<td>15ME751</td>
<td>03</td>
<td>3-0-0</td>
<td>80</td>
<td>20</td>
</tr>
</tbody>
</table>

Course Objective

Students will learn

1. Basics of electronic control of internal combustion engines and the drives
2. Understand principle of working of sensors and actuators used in automobiles for control
3. Diagnostics and safety systems in automobiles

Module 1


Module 2
Control Systems - Automotive Control System applications of Sensors and Actuators – Typical Electronic Engine Control System, Variables to be measured


Automotive Actuators – Solenoid, Fuel Injector, EGR Actuator, Ignition System

Module 3


Control Units – Operating conditions, Design, Data processing, Programming, Digital modules in the Control unit, Control unit software.

Module 4

Automotive Networking – Bus Systems – Classification, Applications in the vehicle, Coupling of networks, Examples of networked vehicles (Text 2: Pg. 85-91), Buses - CAN Bus, LIN Bus, MOST Bus, Bluetooth, FlexRay, Diagnostic Interfaces.

Vehicle Motion Control – Typical Cruise Control System, Digital Cruise Control System, Digital Speed Sensor, Throttle Actuator, Digital Cruise Control configuration, Cruise Control Electronics (Digital only), Antilock
Module 5


**Course Outcomes**

1. Explain the electronics systems used for control of automobiles
2. Select sensors, actuators and control systems used in automobiles
3. Diagnose the faults in the sub systems and systems used automobile

**Text Books:**

FRACTURE MECHANICS

<table>
<thead>
<tr>
<th>Course</th>
<th>Code</th>
<th>Credits</th>
<th>L-T-P</th>
<th>Assessment</th>
<th>Exam Duration</th>
</tr>
</thead>
<tbody>
<tr>
<td>Fracture Mechanics</td>
<td>15ME752</td>
<td>03</td>
<td>3-0-0</td>
<td>80</td>
<td>20</td>
</tr>
</tbody>
</table>

Course Objective:
Fracture mechanics provides a methodology for prediction, prevention and control of fracture in materials, components and structures.
It provides a background for damage tolerant design.
It quantifies toughness as materials resistance to crack propagation.

Course Content:

Module 1.

Module 2.

Module 3.

Module 4.
Module 5.


Course Outcome:

At the end of the course students will:
1. Develop basic fundamental understanding of the effects of cracklike defects on the performance of aerospace, civil, and mechanical Engineering structures.
2. Learn to select appropriate materials for engineering structures to insure damage tolerance.
3. Learn to employ modern numerical methods to determine critical crack sizes and fatigue crack propagation rates in engineering structures.
4. Gain an appreciation of the status of academic research in field of fracture mechanics.

Text Books

Reference Books
MECHATRONICS

<table>
<thead>
<tr>
<th>Course</th>
<th>Code</th>
<th>Credits</th>
<th>L-T-P</th>
<th>Assessment</th>
<th>Exam Duration</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mechatronics</td>
<td>15ME753</td>
<td>03</td>
<td>3-0-0</td>
<td>80 SEE 20 CIA</td>
<td>3 Hrs</td>
</tr>
</tbody>
</table>

Course objectives:

1. Understand the evolution and development of Mechatronics as a discipline.
2. Substantiate the need for interdisciplinary study in technology education.
3. Understand the applications of microprocessors in various systems and to know the functions of each element.
4. Demonstrate the integration philosophy in view of Mechatronics technology.

MODULE -1
Introduction: Definition, Multidisciplinary Scenario, Evolution of Mechatronics, Design of Mechatronics system, Objectives, advantages and disadvantages of Mechatronics.

Transducers and sensors: Definition and classification of transducers. Difference between transducer and sensor, Definition and classification of sensors, Principle of working and applications of light sensors, proximity switches and Hall Effect sensors.

10 Hours

MODULE -2
Microprocessor & Microcontrollers: Introduction, Microprocessor systems, Basic elements of control systems, Microcontrollers, Difference between Microprocessor and Microcontrollers.

Microprocessor Architecture: Microprocessor architecture and terminology-CPU, memory and address, I/O and Peripheral devices, ALU, Instruction and Program, Assembler, Data, Registers, Program Counter, Flags, Fetch cycle, write cycle, state, bus interrupts. Intel’s 8085A Microprocessor.

10 Hours

MODULE -3
Programmable logic controller: Introduction to PLC’s, basic structure, Principle of operation, Programming and concept of ladder diagram, concept of latching & selection of a PLC.


10 Hours

MODULE -4
Mechanical actuation systems: Mechanical systems, types of motion, Cams, Gear trains, Ratchet & Pawl, belt and chain drives, mechanical aspects of motor selection.

Electrical actuation systems: Electrical systems, Mechanical switches, Solenoids, Relays, DC/AC Motors, Principle of Stepper Motors & servomotors.

10 Hours

MODULE -5
Pneumatic and hydraulic actuation systems: Actuating systems, Pneumatic and hydraulic systems, Classifications of Valves, Pressure relief valves, Pressure regulating/reducing valves, Cylinders and rotary actuators.

DCV & FCV: Principle & construction details, types of sliding spool valve,
solenoid operated, Symbols of hydraulic elements, components of hydraulic system, functions of various units of hydraulic system. Design of simple hydraulic circuits for various applications. 10 Hours

Course outcomes:

On completion of this subject, students will be able to:
1. Illustrate various components of Mechatronics systems.
2. Assess various control systems used in automation.
3. Develop mechanical, hydraulic, pneumatic and electrical control systems.

TEXT BOOKS:

REFERENCE BOOKS:

E- Learning
- VTU, E-learning

Scheme of Examination:
Two question to be set from each module. Students have to answer five full questions, choosing at least one full question from each module.
Course Code: 15ME754

Course Objective:

1. To enable the students to understand the theoretical principles of vibration and vibration analysis techniques for the practical solution of vibration problems.
2. To enable the students to understand the importance of vibrations in mechanical design of machine parts subject to vibrations.

Module 1

Forced Vibrations (1 DOF): Introduction, analysis of forced vibration with constant harmonic excitation, MF, rotating and reciprocating unbalances, excitation of support (relative and absolute amplitudes), force and motion transmissibility, energy dissipated due to damping and numerical problems.

Systems with 2 DOF: Principal modes of vibrations, normal mode and natural frequencies of systems (Damping is not included), simple spring-mass systems, masses on tightly stretched strings, double pendulum, tensional systems, combined rectilinear and angular systems, geared systems and numerical problems.

Module 2


Modal Analysis and Condition Monitoring: Signal analysis, dynamic testing of machines and structures, experimental modal analysis, machine condition monitoring and diagnosis.

Module 3

Vibration Measuring Instruments and Whirling of Shafts: Seismic instruments, vibrometers, accelerometer, frequency measuring instruments and numerical. Whirling of shafts with and without damping.


Module 4


Random Vibrations: Random phenomena Time averaging and expected value, Frequency response function, Probability distribution, Correlation, Power spectrum and power spectral density, Fourier transforms and response.

Module 5


Continuous Systems: Vibration of string, longitudinal vibration of rods, Torsional vibration of rods, Euler equation for beams.
Course outcomes:
On completion of this subject, students will be able to:
4. Understand and characterize the single and multi degrees of freedom systems subjected to free and forced vibrations with and without damping.
5. Understand the method of vibration measurements and its controlling.
6. Understand the concept of dynamic vibrations of a continuous systems.

TEXT BOOKS:
5. Mechanical Vibrations, W.T. Thomson W.T.- Prentice Hill India

REFERENCE BOOKS:

E- Learning
• VTU, E- learning

Scheme of Examination:
Two question to be set from each module. Students have to answer five full questions, choosing at least one full question from each module.
# DESIGN LABORATORY

<table>
<thead>
<tr>
<th>Course</th>
<th>Code</th>
<th>Credits</th>
<th>L-T-P</th>
<th>Assessment</th>
<th>Exam Duration</th>
</tr>
</thead>
<tbody>
<tr>
<td>Design Laboratory</td>
<td>15MEL76</td>
<td>02</td>
<td>1-0-2</td>
<td>80</td>
<td>20</td>
</tr>
</tbody>
</table>

**Prerequisites:** Knowledge of Dynamics and Machines and Design of Machine Elements

## COURSE OBJECTIVES:

**Students are expected-**

1. To understand the natural frequency, logarithmic decrement, damping ratio and damping.
2. To understand the balancing of rotating masses.
3. To understand the concept of the critical speed of a rotating shaft.
4. To understand the concept of stress concentration using Photo elasticity.
5. To understand the equilibrium speed, sensitiveness, power and effort of Governor.

## PART –A

1. Determination of natural frequency, logarithmic decrement, damping ratio and damping Co-efficient in a single degree of freedom vibrating systems (longitudinal and torsional)
2. Determination of critical speed of rotating shaft.
4. Determination of fringe constant of Photo-elastic material using Circular disk subjected diametric compression, Pure bending specimen (four point bending)
5. Determination of stress concentration using Photo elasticity for simple components like Plate with hole under tension or bending, circular disk with circular hole under compression, 2-d crane hook.

## PART –B

1. Determination of equilibrium speed, sensitiveness, power and effort of Porter/ Proel / Hartnell Governor. (at least one)
2. Determination of pressure distribution in Journal bearing
3. Determination of principle stresses and strain in a member subjected to combined loading using strain rosettes.
4. Determination of stresses in curved beam using strain gauge.
5. Experiments on Gyroscope (Demonstration only)
COURSE OUTCOMES

At the end of the course, the students will be able to:

1. To understand the working principles of machine elements such as Governors, Gyroscopes etc.,
2. To identify forces and couples in rotating mechanical system components.
3. To identify vibrations in machine elements and design appropriate damping methods and to determine the critical speed of a rotating shaft.
4. To measure strain in various machine elements using strain gauges.
5. To determine the minimum film thickness, load carrying capacity, frictional torque and pressure distribution of journal bearing.
6. To determine strain induced in a structural member using the principle of photo-elasticity.

Scheme of Examination:

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>One question from Part A</td>
<td>32 Marks</td>
</tr>
<tr>
<td>One question from part B</td>
<td>32 Marks</td>
</tr>
<tr>
<td>Viva- Voce</td>
<td>16 Marks</td>
</tr>
<tr>
<td><strong>Total</strong></td>
<td><strong>80 Marks</strong></td>
</tr>
</tbody>
</table>

Reference Books:


**COMPUTER INTEGRATED MANUFACTURING LAB**

<table>
<thead>
<tr>
<th>Course</th>
<th>Code</th>
<th>Credits</th>
<th>L-T-P</th>
<th>Assessment</th>
<th>Exam Duration</th>
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</thead>
<tbody>
<tr>
<td>Computer Integrated</td>
<td>15MEL77</td>
<td>02</td>
<td>1-0-2</td>
<td>80</td>
<td>20</td>
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<tr>
<td>Manufacturing LAB</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>3Hrs</td>
</tr>
</tbody>
</table>

**Course Objectives:**

<table>
<thead>
<tr>
<th>CLO1</th>
<th>To expose the students to the techniques of CNC programming and cutting tool path generation through CNC simulation software by using G-Codes and M-codes.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CLO2</td>
<td>To educate the students on the usage of CAM packages.</td>
</tr>
<tr>
<td>CLO3</td>
<td>To make the students understand the importance of automation in industries through exposure to FMS, Robotics, and Hydraulics and Pneumatics.</td>
</tr>
</tbody>
</table>

**Part-A**

- **Manual CNC part programming** for 2 turning and 2 milling parts. Selection and assignment of tools, correction of syntax and logical errors, and verification of tool path.
- **CNC part programming using CAM packages.** Simulation of Turning, Drilling, Milling operations.
  
  3 typical simulations to be carried out using simulation packages like: CademCAMLab-Pro, Master-CAM.

  Program generation using software. Optimize spindle power, torque utilization, and cycle time. Generation and printing of shop documents like process and cycle time sheets, tool list, and tool layouts. Cut the part in single block and auto mode and measure the virtual part on screen. Post processing of CNC programs for standard CNC control systems like FANUC, SINUMERIC and MISTUBISHI.

**Part B**

(Only for Demo/Viva voce)

- **FMS (Flexible Manufacturing System):** Programming of Automatic storage and Retrieval system (ASRS) and linear shuttle conveyor Interfacing CNC lathe, milling with loading unloading arm and ASRS to be carried out on simple components.

(Only for Demo/Viva voce)

- **Robot programming:** Using Teach Pendent & Offline programming to perform pick and place, stacking of objects (2 programs).
- **Pneumatics and Hydraulics, Electro-Pneumatics:** 3 typical experiments on Basics of these topics to be conducted.

**Course Outcomes:**
After studying this course, students will be able to:

<table>
<thead>
<tr>
<th>CLO1</th>
<th>Generate CNC Lathe part program for Turning, Facing, Chamfering, Grooving, Step turning, Taper turning, Circular interpolation etc.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CLO2</td>
<td>Generate CNC Mill Part programming for Point to point motions, Line motions, Circular interpolation, Contour motion, Pocket milling- circular, rectangular, Mirror commands etc.</td>
</tr>
<tr>
<td>CLO3</td>
<td>Use Canned Cycles for Drilling, Peck drilling, Boring, Tapping, Turning, Facing, Taper turning Thread cutting etc.</td>
</tr>
<tr>
<td>CLO4</td>
<td>Simulate Tool Path for different Machining operations of small components using CNC Lathe &amp; CNC Milling Machine.</td>
</tr>
<tr>
<td>CLO5</td>
<td>Use high end CAM packages for machining complex parts; use state of art cutting tools and related cutting parameters; optimize cycle time.</td>
</tr>
<tr>
<td>CLO6</td>
<td>Understand &amp; write programs for Robotcontrol; understand the operating principles of hydraulics, pneumatics and electropneumatic systems. Apply this knowledge to automate &amp; improve efficiency of manufacturing.</td>
</tr>
</tbody>
</table>

**Scheme for Examination:**
Two Questions from Part A - 60 Marks (30 +30)  
Viva-Voce - 20 Marks  
Total: 80 Marks
<table>
<thead>
<tr>
<th>Course</th>
<th>Code</th>
<th>Credits</th>
<th>L-T-P</th>
<th>Assessment</th>
<th>Exam Duration</th>
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</thead>
<tbody>
<tr>
<td>Project Work, Phase I</td>
<td>15MEP78</td>
<td>2</td>
<td>0-3-0</td>
<td>SEE 100 CIA</td>
<td>-</td>
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